

EE482: Digital Signal Processing Applications

Numerical effects

Outline

- Random Variables
- Fixed-Point Numbers
- Quantization Errors
- Arithmetic Errors

Random Variables

- Function that maps from a sample space to a real value
 - $x: S \rightarrow \mathbb{R}$
 - x – random variable (does not have a value)
 - S – sample space
- Cumulative distribution function (CDF)
 - $F(X) = P(x \leq X)$
 - E.g. probability $\{x \leq X\}$
- Probability density function (PDF)
 - $f(X) = \frac{dF(X)}{dX}$
 - $\int_{-\infty}^{\infty} f(X) dX = 1$
 - $P(X_1 < x \leq X_2) = F(X_2) - F(X_1) = \int_{X_1}^{X_2} f(X) dX$
 - For discrete x , takes values X_i , $i = 1, 2, 3, \dots$
 - $p_i = P(x = X_i)$

Uniform Random Variable

- Variable takes on value in a range with equal probability

- $$f(X) = \begin{cases} \frac{1}{X_2 - X_1} & X_1 \leq x \leq X_2 \\ 0 & \text{else} \end{cases}$$

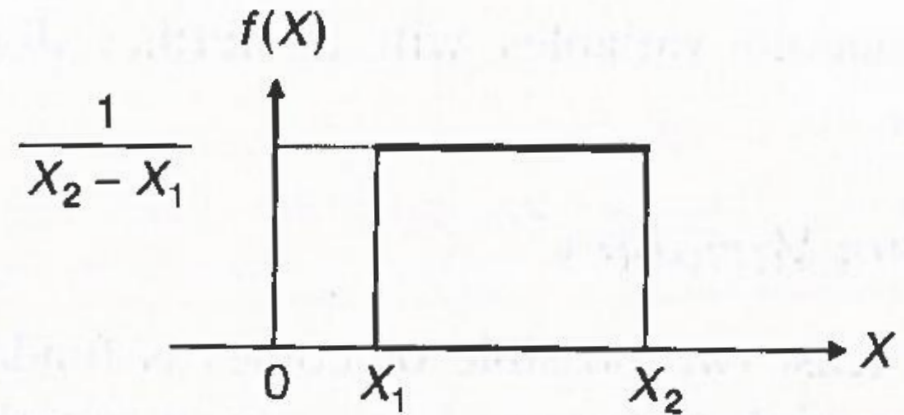


Figure 2.17 The uniform density function

- Be sure you can calculate mean and variance

Statistics of Random Variables

- Expected value (mean)
 - $m_x = E[x]$ expectation operator
 - $m_x = \int_{-\infty}^{\infty} Xf(X)dX$ continuous
 - $m_x = \sum_i X_i p_i$ discrete
 - Can be can computed with `mean.m`
- Variance (spread around mean)
 - $\sigma_x^2 = E[(x - m_x)^2] = E[x^2] - m_x^2$
 - $\sigma_x^2 = \int_{-\infty}^{\infty} (X - m_x)^2 f(X)dX$ continuous
 - $\sigma_x^2 = \sum_i p_i (X_i - m_x)^2$ discrete
 - For $m_x = 0$,
 - $\sigma_x^2 = E[x^2] = P_x$ second moment, power

Fixed-Point Numerical Effects

- Fractional numbers are represented in 2's complement with $B = M + 1$ bits

- $x = b_0.b_1b_2 \dots b_{M-1}b_M$

Diagram illustrating the bit positions in the fixed-point representation $x = b_0.b_1b_2 \dots b_{M-1}b_M$:

- b_0 is the **sign bit**.
- The dot between b_0 and b_1 is the **binary point**.
- b_{M-1} is the **msb** (most significant bit).
- b_M is the **lsb** (least significant bit).

- $b_0 = \begin{cases} 0 & x \geq 0 \quad \text{positive} \\ 1 & x < 0 \quad \text{negative} \end{cases}$

- value = $-b_0 + \sum_{m=1}^M b_m 2^{-m}$

- $-1 \leq x \leq (1 - 2^{-M})$
 - Unbalanced range with more negative than positive numbers

General Fractional Format Qn.m

- $$x = b_0 b_1 b_2 \dots b_n \cdot b_1 b_2 \dots b_M$$

↑
sign bit
integer
↑
binary point
fractional

- Example 2.25

- $x = 0100\ 1000\ 0001\ 1000b = 0x4818$

- Q0.15

- $\square x = 2^{-1} + 2^{-4} + 2^{-11} + 2^{-12} = 0.56323$

- Q2.13

- $\square x = 2^1 + 2^{-2} + 2^{-9} + 2^{-10} = 2.25293$

- Q5.10

- $\square x = 2^4 + 2^1 + 2^{-6} + 2^{-7} = 18.02344$

Finite Word Length Effects

1. Quantization errors
 - Signal quantization
 - Coefficient quantization
2. Arithmetic errors
 - Roundoff (truncation)
 - Overflow

Signal Quantization

- ADC conversion of sampled signals to fixed levels
- Using Q15 and B bits
 - Dynamic range $-1 \leq x < 1$
 - Quantization step
 - $\Delta = \frac{2}{2^B} = 2^{-B+1} = 2^{-M}$
- Quantization error
 - $e(n) = x(n) - x_B(n)$
 - $x_B(n) = Q[x(n)]$
 - $|e(n)| \leq \frac{\Delta}{2} = 2^{-B}$ (rounding)
 - Error dependent on word length B
 - More bits for better resolution, less error (noise)
- Signal to quantization noise (SQNR)
 - $SQNR = \frac{\sigma_x^2}{\sigma_e^2} = 3.2^{2B} \sigma_x^2$
 - $SQNR = 4.77 + 6.02B + 10 \log_{10} \sigma_x^2 \text{ dB}$

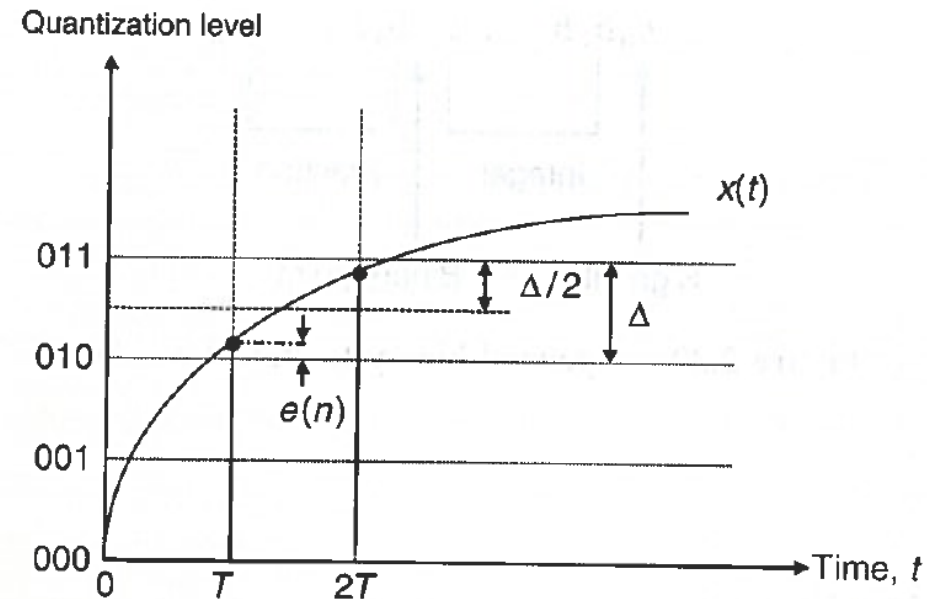


Figure 2.21 Quantization process related to a 3-bit ADC

Coefficient Quantization

- Same error issues as for signals
- Results in movement of the locations of poles/zeros
 - Changes system function polynomials
 - Can lead to instability if poles go outside the unit circle
 - Generally, more a problem with IIR filters
- Can limit coefficient quantization effects by using lower-order filters
 - Use of cascade and parallel filter structures

Roundoff Noise

- A product must be represented in B bits by rounding (truncation)

$$\begin{array}{ccccc} \square & y(n) & = & \alpha x(n) & \\ & \uparrow & & \uparrow & \swarrow \\ & 2B \text{ bits} & & B \text{ bits} & B \text{ bits} \end{array}$$

- Error model
 - $y(n) = Q[\alpha x(n)] = \alpha x(n) + e(n)$
 - $e(n)$ is uniformly distributed zero mean noise (rounding)

Overflow

- $y(n) = x_1(n) + x_2(n)$
 - $-1 \leq x_i(n) < 1$
 - $-1 \leq y(n) < 1$
- Overflow occurs when the sum cannot fit in the word container
- Signals need to be scaled to prevent overflow

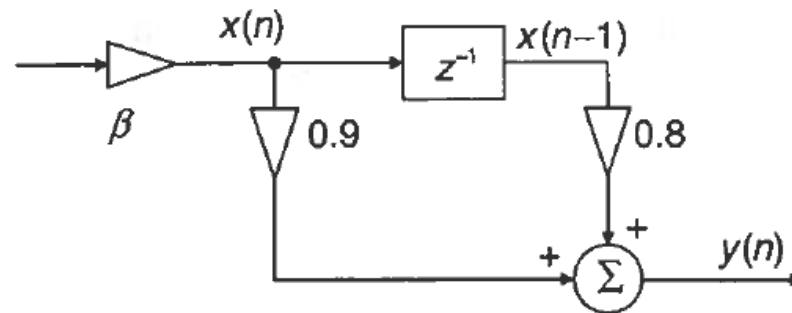


Figure 2.24 Block diagram of simple FIR filter with scaling factor β

- Notice: this reduces the SQNR
 - $SQNR = 10 \log_{10} \left(\frac{\beta^2 \sigma_x^2}{\sigma_e^2} \right)$
 - $SQNR = 4.77 + 6.02B + 10 \log_{10} \sigma_x^2 + \underbrace{20 \log_{10} \beta}_{\text{negative}} \text{ dB}$