Power System Representation: Voltage-Current Relations, and Power Flow Analysis

EE 340

One-line diagram (simple power system)



- Typical information included:
 - Device ratings and impedances
 - Load demand in terms of real and reactive powers.

Per-unit equivalent circuit

- Real power systems are convenient to analyze using their perphase (since its is a balanced three-phase) per-unit (since there are many transformers) equivalent circuits.
- Recall: given the base apparent power (3—phase) and base voltage (line-to-line), the base current and base impedance are given by

$$I_{base} = \frac{S_{3\phi,base}}{\sqrt{3}V_{LL,base}}$$
$$Z_{base} = \frac{V_{LL,base}}{\sqrt{3}I_{base}} = \frac{\left(V_{LL,base}\right)^2}{S_{3\phi,base}}$$

Per-unit system

- The base apparent power and base voltage are specified at a point in the circuit, and the other values are calculated from them.
- The base voltage varies by the voltage ratio of each transformer in the circuit but the base apparent power stays the same through the circuit.
- The per-unit impedance may be transformed from one base to another as

$$Per-unit \ Z_{new} = per-unit \ Z_{old} \left(\frac{V_{old}}{V_{new}}\right)^2 \left(\frac{S_{new}}{S_{old}}\right)$$

Example

Example 10.2: a power system consists of one synchronous generator and one synchronous motor connected by two transformers and a transmission line. Create a per-phase, per-unit equivalent circuit of this power system using a base apparent power of 100 MVA and a base line voltage of the generator G_1 of 13.8 kV. Given that:

*G*₁ ratings: 100 MVA, 13.8 kV, *R* = 0.1 pu, *X_s* = 0.9 pu; *T*₁ ratings: 100 MVA, 13.8/110 kV, *R* = 0.01 pu, *X_s* = 0.05 pu; *T*₂ ratings: 50 MVA, 120/14.4 kV, *R* = 0.01 pu, *X_s* = 0.05 pu; *M* ratings: 50 MVA, 13.8 kV, *R* = 0.1 pu, *X_s* = 1.1 pu; L₁ impedance: *R* = 15 Ω, *X* = 75 Ω.



Example (cont.)



 $R_{M2,pu} = 0.1(14.8/13.2)^{2}(100/50) = 0.219 \text{ per unit} \qquad R_{T2,pu} = 0.01(14.4/13.2)^{2}(100/50) = 0.238 \text{ per unit} \\ X_{M2,pu} = 1.1(14.8/13.2)^{2}(100/50) = 2.405 \text{ per unit} \qquad X_{T2,pu} = 0.05(14.4/13.2)^{2}(100/50) = 0.119 \text{ per unit}$



Node equations

- Once the per-unit equivalent circuit is created, it can be used to determine the voltages, currents, and powers at various points .
- The most common technique used to solve such circuits is nodal analysis. To simplify the equations,
 - Replace the generators by their Norton equivalent circuits
 - Replace the impedances by their equivalent admittances
 - Represent the loads by the current they draw (for now)



Node equations

- According to Kirchhoff's current flow law (KCL), the sum of all currents entering any node equals to the sum of all currents leaving the node.
- KCL can be used to establish and solve a system of simultaneous equations with the unknown node voltages.
- Assuming that the current from the current sources are entering each node, and that all other currents are leaving the node, applying the KCL to the 3 nodes yields

$$\begin{split} & \left(V_1 - V_2\right)Y_a + \left(V_1 - V_3\right)Y_b + V_1Y_d = I_1 \\ & \left(V_2 - V_1\right)Y_a + \left(V_2 - V_3\right)Y_c + V_2Y_e = I_2 \\ & \left(V_3 - V_1\right)Y_b + \left(V_3 - V_2\right)Y_c + V_3Y_f = I_3 \end{split}$$

Node equations – the Y_{bus} matrix

• In matrix from,

$$\begin{bmatrix} Y_a + Y_b + Y_d & -Y_a & -Y_b \\ -Y_a & Y_a + Y_c + Y_e & -Y_c \\ -Y_b & -Y_c & Y_b + Y_c + Y_f \end{bmatrix} \begin{bmatrix} V_1 \\ V_2 \\ V_3 \end{bmatrix} = \begin{bmatrix} I_1 \\ I_2 \\ I_3 \end{bmatrix}$$

Which is an equation of the form:

$$Y_{bus}V = I$$

where Y_{bus} is the bus admittance matrix of a system, which has the form:

$$Y_{bus} = \begin{bmatrix} Y_{11} & Y_{12} & Y_{13} \\ Y_{21} & Y_{22} & Y_{23} \\ Y_{31} & Y_{32} & Y_{33} \end{bmatrix}$$

 Y_{bus} has a regular form that is easy to calculate:

- 1) The diagonal elements Y_{ii} equal the sum of all admittances connected to node *i*.
- Other elements Y_{ij} equal to the negative admittances connected to nodes I and j.

The diagonal elements of Y_{bus} are called the self-admittance or driving-point admittances of the nodes; the off-diagonal elements are called the mutual admittances or transfer admittances of the nodes.

\mathbf{Y}_{bus} and \mathbf{Z}_{bus} matrices of a power network

Inverting the bus admittance matrix Y_{bus} yields the bus impedance matrix:

$$Z_{bus} = Y_{bus}^{-1}$$

Simple technique for constructing Y_{bus} is only applicable for components that are not mutually coupled. The technique applicable to mutually coupled components can be found elsewhere.

Once Y_{bus} is calculated, the solution

or

$$V = Y_{bus}^{-1}I$$
$$V = Z_{bus}I$$

Example





Example (cont.)

The resulting admittance matrix is:

$$Y_{bus} = \begin{bmatrix} -j12.576 & j5.0 & 0 & j6.667 \\ j5.0 & -j12.5 & j5.0 & j2.5 \\ 0 & j5.0 & -10.625 & j5.0 \\ j6.667 & j2.5 & j5.0 & -j14.167 \end{bmatrix}$$

The current vector for this circuit is:

$$I = \begin{bmatrix} 1.0 \angle -80^{\circ} \\ 0 \\ 0.563 \angle -112^{\circ} \\ 0 \end{bmatrix}$$

The solution to the system of equations will be

$$V = Y_{bus}^{-1}I = \begin{bmatrix} 0.989 \angle -0.60^{\circ} \\ 0.981 \angle -1.58^{\circ} \\ 0.974 \angle -2.62^{\circ} \\ 0.982 \angle -1.48^{\circ} \end{bmatrix} V$$

Problems

- 10.3
- 10.5
- 10.7, 10.8, 10.9

Power-flow analysis equations

The basic equation for power-flow analysis is derived from the nodal analysis equations for the power system: For example, for a 4-bus system,



where Y_{ij} are the elements of the bus admittance matrix, V_i are the bus voltages, and I_i are the currents injected at each node. The node equation at bus *i* can be written as

$$I_i = \sum_{j=1}^n Y_{ij} V_j$$

Relationship between per-unit real and reactive power supplied to the system at bus i and the per-unit current injected into the system at that bus:

$$S_i = V_i I_i^* = P_i + jQ_i$$

where V_i is the per-unit voltage at the bus; I_i^* - complex conjugate of the per-unit current injected at the bus; P_i and Q_i are per-unit real and reactive powers. Therefore,

$$I_{i}^{*} = (P_{i} + jQ_{i})/V_{i} \implies I_{i} = (P_{i} - jQ_{i})/V_{i}^{*}$$
$$\implies P_{i} - jQ_{i} = V_{i}^{*}\sum_{j=1}^{n}Y_{ij}V_{j} = \sum_{j=1}^{n}Y_{ij}V_{j}V_{i}^{*}$$

Power flow equations

Let
$$Y_{ij} = |Y_{ij}| \angle \theta_{ij}$$
 and $V_i = |V_i| \angle \delta_i$
Then $P_i - jQ_i = \sum_{j=1}^n |Y_{ij}| |V_j| |V_i| \angle (\theta_{ij} + \delta_j - \delta_i)$
Hence, $P_i = \sum_{j=1}^n |Y_{ij}| |V_j| |V_i| \cos(\theta_{ij} + \delta_j - \delta_i)$
and $Q_i = -\sum_{j=1}^n |Y_{ij}| |V_j| |V_i| \sin(\theta_{ij} + \delta_j - \delta_i)$

Formulation of power-flow study

- There are 4 variables that are associated with each bus:
 - о **Р**,
 - 0 Q,
 - 0 V,
 - ο δ.
- Meanwhile, there are two power flow equations associated with each bus.
- In a power flow study, two of the four variables are defined an the other two are unknown. That way, we have the same number of equations as the number of unknown.
- The known and unknown variables depend on the type of bus.

Formulation of power-flow study

Each bus in a power system can be classified as one of three types:

- Load bus (P-Q bus) a buss at which the real and reactive power are specified, and for which the bus voltage will be calculated. All busses having no generators are load busses. In here, V and δ are unknown.
- 2. Generator bus (P-V bus) a bus at which the magnitude of the voltage is defined and is kept constant by adjusting the field current of a synchronous generator. We also assign real power generation for each generator according to the economic dispatch. In here, Q and δ are unknown
- Slack bus (swing bus) a special generator bus serving as the reference bus. Its voltage is assumed to be fixed in both magnitude and phase (for instance, 1∠0° pu). In here, P and Q are unknown.

Formulation of power-flow study

- Note that the power flow equations are non-linear, thus cannot be solved analytically. A numerical iterative algorithm is required to solve such equations. A standard procedure follows:
 - 1. Create a bus admittance matrix Y_{bus} for the power system;
 - 2. Make an initial estimate for the voltages (both magnitude and phase angle) at each bus in the system;
 - 3. Substitute in the power flow equations and determine the deviations from the solution.
 - Update the estimated voltages based on some commonly known numerical algorithms (e.g., Newton-Raphson or Gauss-Seidel).
 - 5. Repeat the above process until the deviations from the solution are minimal.

Example

Consider a 4-bus power system below. Assume that

- bus 1 is the slack bus and that it has a voltage $V1 = 1.0 \angle 0^{\circ}$ pu.
- The generator at bus 3 is supplying a real power P3 = 0.3 pu to the system with a voltage magnitude 1 pu.
- The per-unit real and reactive power loads at busses 2 and 4 are P2
 = 0.3 pu, Q2 = 0.2 pu, P4 = 0.2 pu, Q4 = 0.15 pu.



Example (cont.)

• Y-bus matrix (refer to example in book)

$$Y_{bus} = \begin{bmatrix} 1.7647 - j7.0588 & -0.5882 + j2.3529 & 0 & -1.1765 + j4.7059 \\ -0.5882 + j2.3529 & 1.5611 - j6.6290 & -0.3846 + j1.9231 & -0.5882 + j2.3529 \\ 0 & -0.3846 + j1.9231 & 1.5611 - j6.6290 & -1.1765 + j4.7059 \\ -1.1765 + j4.7059 & -0.5882 + j2.3529 & -1.1765 + j4.7059 & 2.9412 - j11.7647 \end{bmatrix}$$

 $V_1 = 1.0 \angle 0^{\circ} pu$

• Power flow solution: $V_2 = 0.964 \angle -0.97^\circ pu$ $V_3 = 1.0 \angle 1.84^\circ pu$ $V_4 = 0.98 \angle -0.27^\circ pu$

 By knowing the node voltages, the power flow (both active and reactive) in each branch of the circuit can easily be calculated.